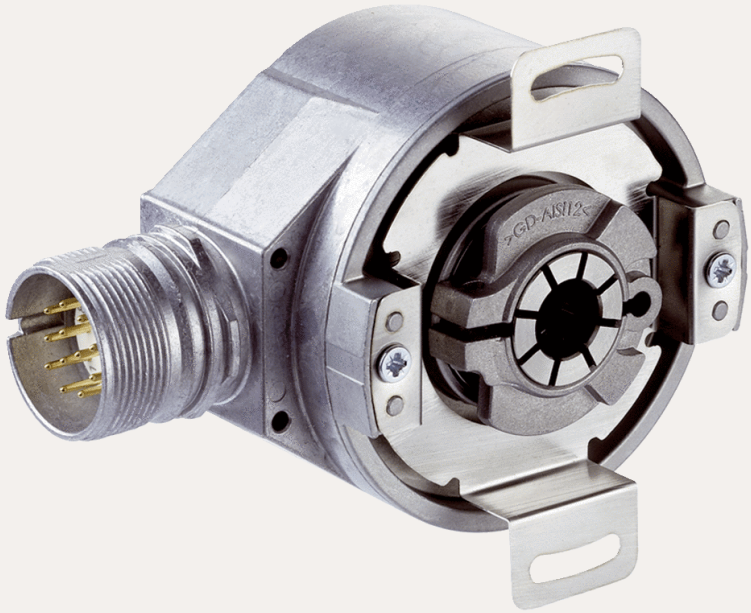
SICK.COM



DATA SHEET

AFM60E-BHAA004096

AFS/AFM60 SSI
Absolute encoders

SICK Sensor Intelligence



Illustration may differ

ABSOLUTE ENCODERS

AFM60E-BHAA004096

ORDERING INFORMATION

Type	part no.
AFM60E-BHAA004096	1038933

Further device versions and accessories at www.sick.com/AFS_AFM60_SSI

DETAILED TECHNICAL DATA

SAFETY-RELATED PARAMETERS

$MTTF_D$ (mean time to dangerous failure)	250 years (EN ISO 13849-1) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

PERFORMANCE

Number of steps per revolution (max. resolution)	4,096 (12 bit)
Number of revolutions	4,096 (12 bit)
Max. resolution (number of steps per revolution x number of revolutions)	12 bit x 12 bit (4,096 x 4,096)
Error limits G	0.2° [1]
Repeatability standard deviation σ_r	0.002° [2]

[1] In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

[2] In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

INTERFACES

Communication interface	SSI
Initialization time	50 ms [1]
Position forming time	< 1 µs
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 1 MHz [2]
Set (electronic adjustment)	H-active (L = 0 - 3 V, H = 4,0 - U_s V)

[1] Valid positional data can be read once this time has elapsed.

[2] Minimum, LOW level (Clock +): 250 ns.

CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)

[1] Valid positional data can be read once this time has elapsed.

[2] Minimum, LOW level (Clock +): 250 ns.

ELECTRONICS

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	4.5 ... 32 V
Power consumption	≤ 0.7 W (without load)
Reverse polarity protection	✓

MECHANICS

Mechanical design	Blind hollow shaft
Shaft diameter	15 mm
Characteristics of the shaft	Front clamp
Weight	0.2 kg [1]
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.8 Ncm (+20 °C)
Operating torque	< 0.6 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	≤ 6,000 min^{-1} [2]
Moment of inertia of the rotor	40 gcm^2
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s^2

[1] Based on devices with male connector.

[2] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

AMBIENT DATA

EMC	According to EN 61000-6-2 and EN 61000-6-3 [1]
Enclosure rating	IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) [2]
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	0 °C ... +85 °C
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	50 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

[1] EMC according to the standards quoted is achieved if shielded cables are used.

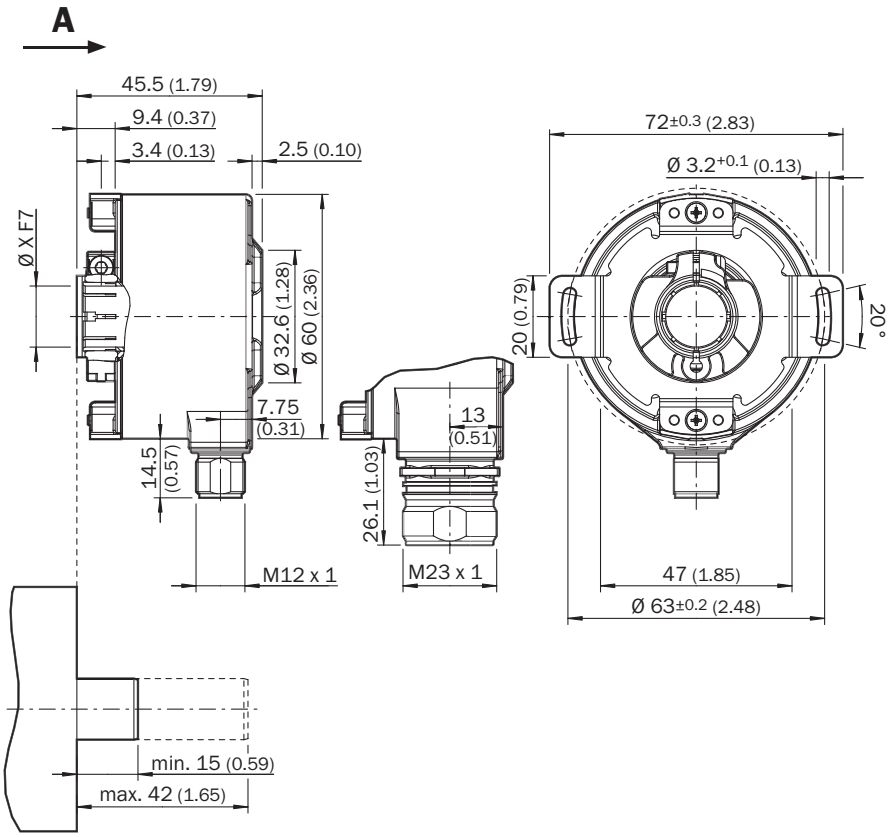
[2] For devices with male connector: with mounted mating connector.

CERTIFICATES

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓

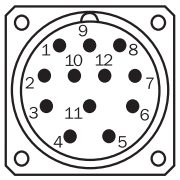
Moroccan declaration of conformity	✓
China RoHS	✓
cULus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

DIMENSIONAL DRAWING



Dimensions in mm (inch)

ANSCHLUSSBELEGUNG M23 MALE CONNECTOR, 12-PIN, SSI/GRAY

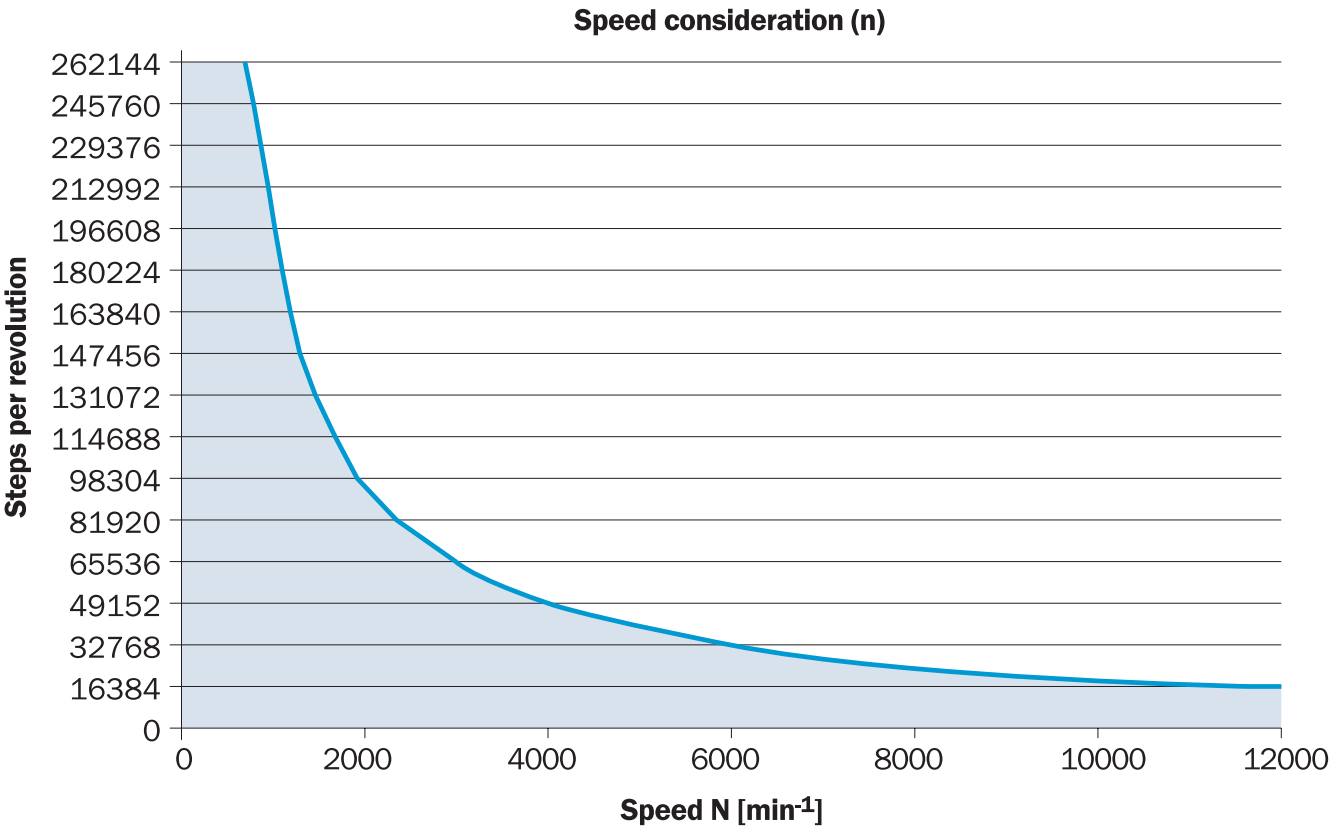


view of M23 male device connector on encoder

PIN	Signal	Explanation
1	GND	Ground connection
2	Data +	Interface signals
3	Clock +	Interface signals
4	N.C.	Not assigned
5	N.C.	Not assigned
6	N.C.	Not assigned
7	N.C.	Not assigned
8	U_s	Operating voltage

PIN	Signal	Explanation
9	SET	Electronic adjustment
10	Data -	Interface signals
11	Clock -	Interface signals
12	V/R	Sequence in direction of rotation
–	Shielding	Shielding connected to housing on encoder side. Connected to ground on control side.

DIAGRAMS



The maximum speed is also dependent on the shaft type.

Further information as well as suitable accessories, example applications and downloads such as CAD dimensional models, operating instructions and software can be found at www.sick.com/1038933

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SICK AT A GLANCE

SICK is a leading global technology company for intelligent sensors and integrated solutions in industrial automation. Our technologies set benchmarks, making your industrial processes more efficient, safer and more sustainable – both in logistics and manufacturing operations.

SICK combines sensor intelligence with industry expertise and certified consulting services. We provide the ideal foundation for scalable as well as tailor-made automation solutions and create added value along the entire value chain. Our close partnerships with our customers are more than just a promise: Together, we optimize productivity, improve quality, protect health and safety, and help build a sustainable future. All with empathy and trust.

Since 1946, we have been developing innovative technologies with passion and a pioneering spirit. With a global network in around 40 countries, SICK has a global presence and is always close by. The company's headquarters are located in Waldkirch near Freiburg, Germany. Our customers benefit from our understanding of both local and global requirements, which enables us to deliver tailor-made solutions

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